

Physics 1

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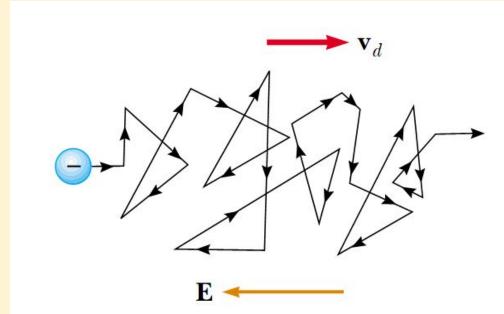
Lecture 11

- Currents in Metals
- The effects of magnetic fields.
- The production and properties of magnetic fields.

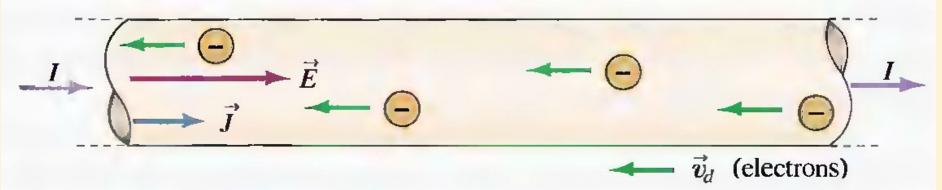
Types of Conductivity

- Conductors are materials through which charge moves easily.
- *Insulators* are materials through which charge does not move easily.
- **Semiconductors** are materials intermediate to conductors and insulators.

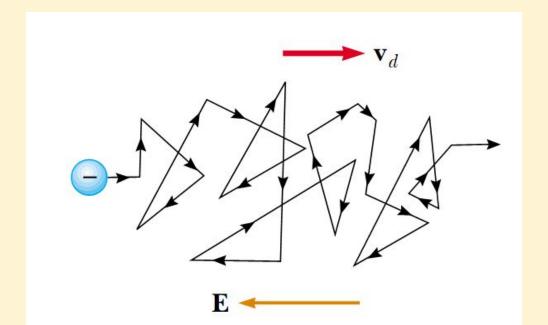
Drift speed of electrons



 There is a zigzag motion of an electron in a conductor. The changes in direction are the result of collisions between the electron and atoms in the conductor. The net motion – drift speed of the electron is opposite the direction of the electric field. So when we consider electric current as a flow of electrons:



in reality there happens zigzag motion of free electrons in the metal:



Current in metals

• Every atom in the metallic crystal gives up one or more of its outer electrons. These electrons are then free to move through the crystal, colliding at intervals with stationary positive ions, then the resistivity is:

$$\rho = m/(ne^2\tau)$$

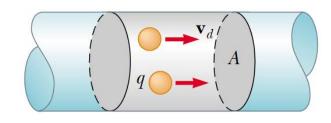
n - the number density of free electrons,

m and **e** – mass and charge of electron,

 τ – average time between collisions.

Resistivity

• A conductor with current:



Current density:

$$J \equiv \frac{I}{A} = nqv_d$$
$$\mathbf{J} = nq\mathbf{v}_d$$

- I electric current
- A the cross-sectional area of the conductor
- v_d drift speed

$$\mathbf{E} = \rho \mathbf{J}$$

 ρ - resistivity

Conductivity

A current density J and an electric field E
are established in a conductor whenever a
potential difference is maintained across the
conductor:

$$\mathbf{J} = \sigma \mathbf{E}$$

 σ is conductivity:

$$\sigma = 1/\rho$$
.

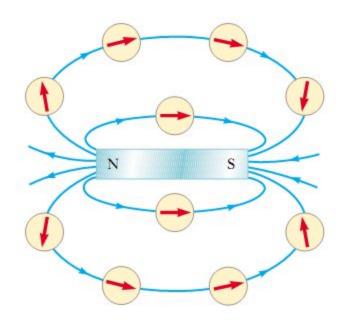
Ohm's law again

• For many materials (including most metals), the ratio of the current density to the electric field is a constant σ that is independent of the electric field producing the current:

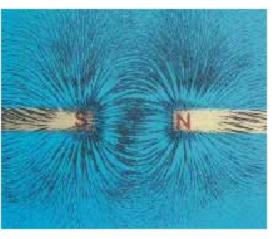
$$J = \sigma E$$

Magnets

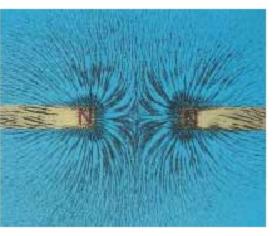
- A single magnetic pole has never been isolated.
 Magnetic poles are always found in pairs.
- The direction of magnetic field is from the North pole to the South pole of a magnet.



Magnet Poles



 Magnet field lines connect unlike poles.



 Magnet field lines repels from like poles.

Magnet Force

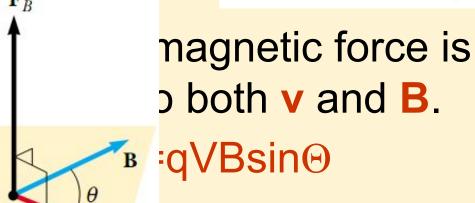
- The magnitude F_R of the magnetic force exerted on the particle is proportional to the charge q and to the speed v of the particle.
- The magnitude and direction of F_B depend on the velocity of the particle and on the magnitude and direction of the magnetic field B.
- When a charged particle moves parallel to the magnetic field vector, the magnetic force acting on the particle is zero.
- When the particle's velocity vector makes any angle ⊕≠0 with the magnetic field, the magnetic force acts in a direction perpendicular to both v and B.
- The magnetic force exerted on a positive charge is in the direction opposite the direction of the magnetic force exerted on a negative charge moving in the same direction.
- The magnitude of the magnetic force exerted on the moving particle is proportional to $\sin \Theta$, where Θ is the angle the particle's velocity vector makes with the direction of B.

The text in the previous slide can be summarized as:

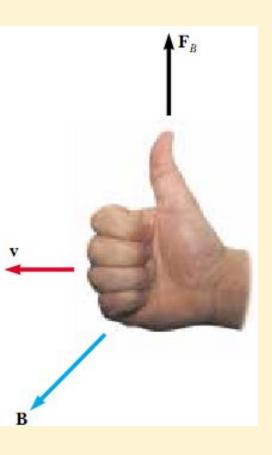
$$\mathbf{F}_B = q\mathbf{v} \times \mathbf{B}$$

So the units for B are:

$$1 T = 1 \frac{N}{C \cdot m/s}$$



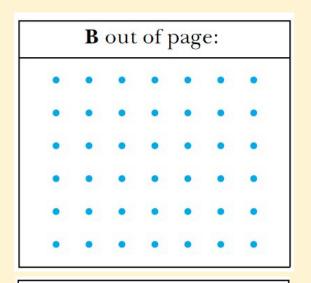
Direction of F_B



Right hand rule:

The fingers point in the direction of v, with B coming out of your palm, so that you can curl your fingers in the direction of **B**. The direction of $\mathbf{v} \times \mathbf{B}$, and the force on a positive charge, is the direction in which the thumb points.

Magnetic field direction

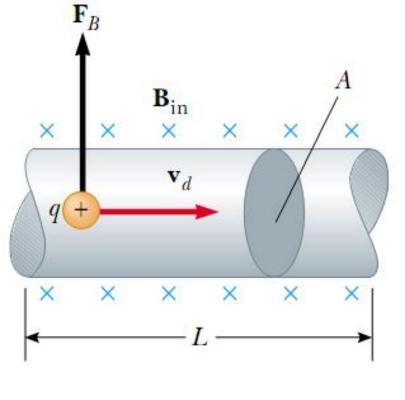


 Magnetic field lines coming out of the paper are indicated by dots, representing the tips of arrows coming outward.

 Magnetic field lines going into the paper are indicated by crosses, representing the feathers of arrows going inward.

Magnetic Force on a Current

 Magnetic force is exerted on a single charge moving in a magnetic field. A current-carrying wire also experiences a force when placed in a magnetic field. This follows from the fact that the current is a collection of many charged particles in motion; hence, the resultant force exerted by the field on the wire is the vector sum of the individual forces exerted on all the charges making up the current. The force exerted on the particles is transmitted to the wire when the particles collide with the atoms making up the wire.



- n is the number density of charged particles q
- v_d is the drift speed of q
- A area of the segment
- L the length of the segment
- Then AL is the volume of the segment, and
- nAL is the number of charged particles q.
- Then the net force acting on all moving charges is:

$$\mathbf{F}_B = (q\mathbf{v}_d \times \mathbf{B}) nAL$$

Arbitrary shaped wire

 The force on a small segment of an arbitrary shaped wire is:

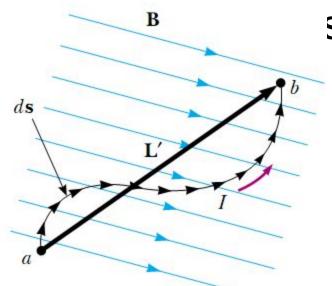
$$d\mathbf{F}_B = I \, d\mathbf{s} \times \mathbf{B}$$

The total force is:

$$\mathbf{F}_B = I \int_a^b d\mathbf{s} \times \mathbf{B}$$

a and b are the end points of the wire.

Curved Wire in a Uniform Magnetic field



s uniform:

$$\mathbf{F}_B = I\left(\int_a^b d\mathbf{s}\right) \times \mathbf{B}$$

$$\mathbf{F}_B = I \mathbf{L}' \times \mathbf{B}$$

 The magnetic force on a curved current-carrying wire in a uniform magnetic field is equal to that on a straight wire connecting the end points and carrying the same current.

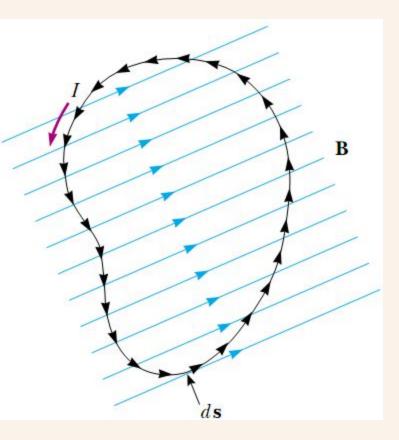
Magnetic force on a straight wire

So, the force on a straight wire in a uniform magnetic field is:

$$\mathbf{F}_B = I\mathbf{L} \times \mathbf{B}$$

- L × B is a vector multiplication.
- Where L is a vector that points in the direction of the current I and has a magnitude equal to the length L of the segment. This expression applies only to a straight segment of wire in a uniform magnetic field.

Loop Wire in a Uniform Magnetic field



 The net magnetic force acting on any closed current loop in a uniform magnetic field is zero:

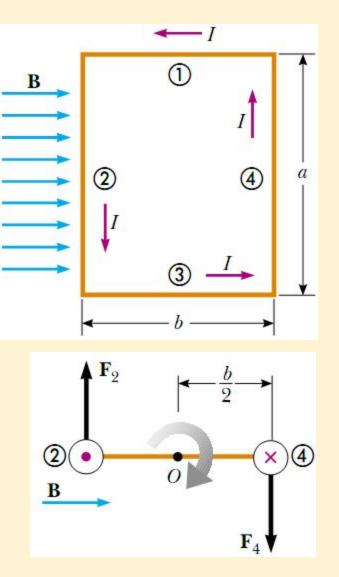
$$\mathbf{F}_B = I\left(\oint d\mathbf{s}\right) \times \mathbf{B}$$

$$\oint d\mathbf{s} = 0$$

Then the net force is zero:

$$\mathbf{F}_{B} = 0$$

Current Loop Torque in a Uniform Magnetic Field

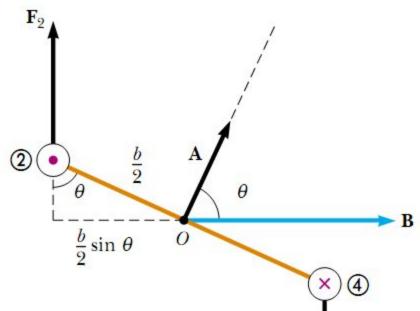


- Overhead view of a rectangular loop in a uniform magnetic field.
 - Sides 1 and 3 are parallel to magnetic field, so only sides 2 and for experiences magnetic forces.
- Magnet forces, acting on sides
 2 and 4 create a torque on the loop.

the loop is:

$$\tau_{\text{max}} = F_2 \frac{b}{2} + F_4 \frac{b}{2} = (IaB) \frac{b}{2} + (IaB) \frac{b}{2} = IabB$$

$$au_{\mathrm{max}} = IAB$$



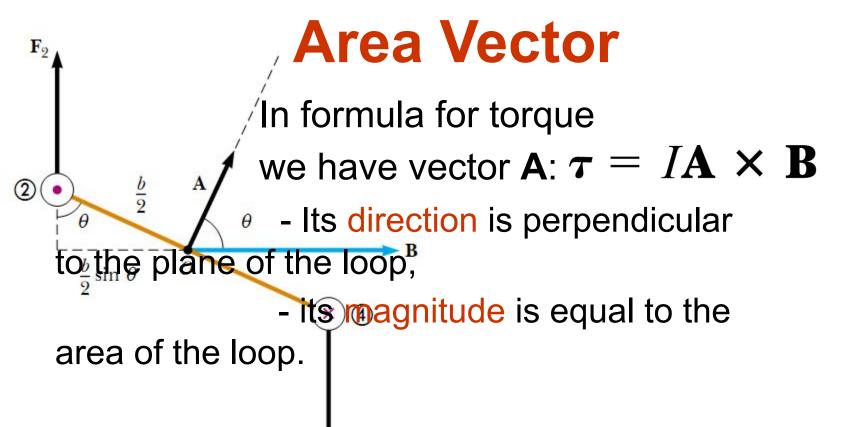
ne loop is not magnetic field, i.e. the etween **A** and **B** is

$$\tau = F_2 \frac{b}{2} \sin \theta + F_4 \frac{b}{2} \sin \theta$$

$$= IaB \left(\frac{b}{2} \sin \theta\right) + IaB \left(\frac{b}{2} \sin \theta\right)$$

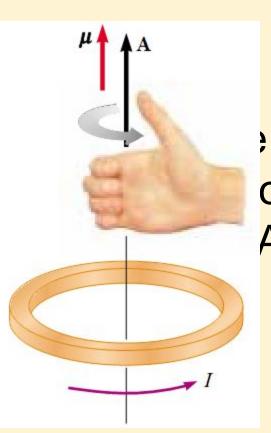
= $IabB \sin \theta = IAB \sin \theta$ Id is:

This formula is correct
$$\tau = IA \times B$$
 tangular loop, but for a planar loop



 We determine the direction of A using the right-hand rule. When you curl the fingers of your right hand in the direction of the current in the loop, your thumb points in the direction of A.

Right – hand rule for loop



direction of the oment is the same as A.

the

Magnetic Moment

 The vector product IA is defined to be the magnetic dipole moment μ (often simply called the "magnetic moment") of the current loop:

$$\mu = IA$$

Then the torque on a current-carrying loop is:

$$\tau = \mu \times \mathbf{B}$$

Potential Energy of a Magnetic Moment

• The potential energy of a system having magnetic dipole μ in the magnetic field \boldsymbol{B} is:

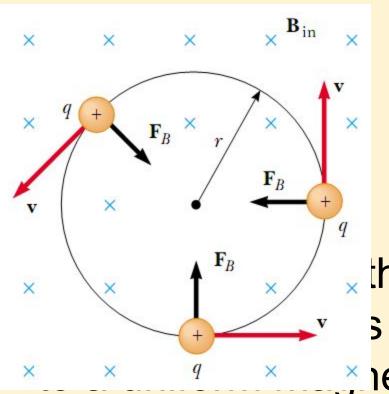
$$U = -\boldsymbol{\mu} \cdot \mathbf{B}$$

• Here we have **scalar** product μ **B**. Then the lowest energy is when μ points as **B**, the highest energy is when μ points opposite **B**:

$$U_{\min} = -\mu B$$

$$U_{\max} = +\mu B$$

Motion of a Charged Particle in a Uniform Magnetic Field



$$F_B = qvB = \frac{mv^2}{r}$$

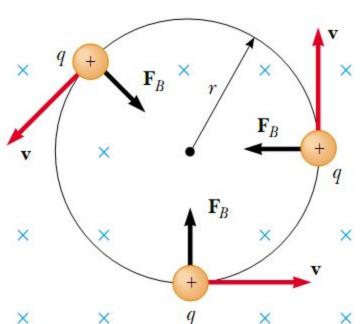
$$r = \frac{mv}{qB}$$

perpendicular

the velocity of a

netic field, the particle moves in a circular path in a plane perpendicular to B. The magnetic force F_B acting on the charge is always directed toward the center of the circle.





$$r = \frac{mv}{qB}$$

the angular velocity

$$\omega = \frac{v}{r} = \frac{qB}{m}$$

here **v** is perpendicular to **B**.

Lorentz Force

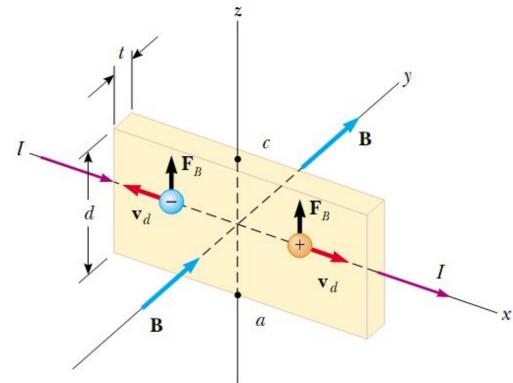
 In the presence of E and B, the force acting on a charged particle is:

$$\mathbf{F} = q\mathbf{E} + q\mathbf{v} \times \mathbf{B}$$

- here q is the charge of the particle,
- v the speed of the particle,
- E electric field vector
- B magnetic field vector

The Hall Effect

 When a current-carrying conductor is placed in a magnetic field, a potential difference is generated in a direction perpendicular to both the current and the magnetic field.



force

has magnitud

balanced

$$qv_dB = qE_{\rm H}$$

$$E_{\rm H} = v_dB$$
 of the conductor:

$$\Delta V_{\rm H} = E_{\rm H} d = v_d B d$$

narge carrier drift speed.

n – charge density: $v_d = \frac{1}{nqA}$

then we obtain the Hall voltage:

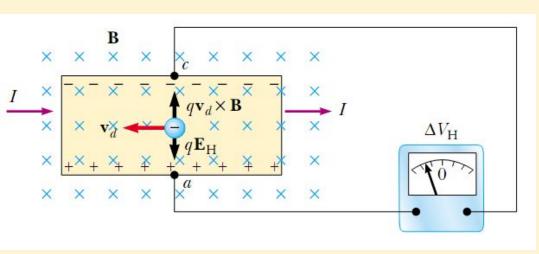
$$\Delta V_{\rm H} = \frac{IBd}{nqA}$$

Using that A=td – cross sectional area of the conductor, t – thickness of the conductor we can obtain:

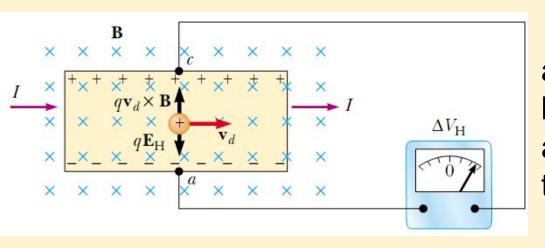
$$\Delta V_{\rm H} = \frac{IB}{nqt} = \frac{R_{\rm H}IB}{t}$$

 $R_{\rm H}$ is the Hall coefficient:

$$R_{\rm H} = 1/(nq)$$



When the charge carriers in a Hall-effect apparatus are negative, the upper edge of the conductor becomes negatively charged, and c is at a lower electric potential than a.



When the charge carriers are positive, the upper edge becomes positively charged, and c is at a higher potential than a.

Units in Si

- Magnetic field
- Electric Field
- Number density
- Torque

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B T= N*s/(C*m)
T= N/(A*m)
E V/m=N/C
n 1/m<sup>3</sup>
τ N*m
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